

$$w_1(r_d)_S = 2r_d e^{-r_d^2 - r_{oa}^2} I_0(2r_{oa}r_d), \quad (r_d, r_{oa} \geq 0), \quad (3.4a)$$

or

$$w_1(\lambda)_S = \frac{2c_0^2}{\hat{r}_0^2} \lambda e^{-\lambda^2 (c_0/\hat{r}_0)^2 - r_{oa}^2} I_0(2r_{oa}c_0\lambda/\hat{r}_0), \quad (r_{oa}, \lambda > 0). \quad (3.4b)$$

When the source is not moving, but its location is unknown to the receiver, the pdf of its location can be usefully expressed alternatively by the density function [9],

$$w_1(\lambda)_S = B_\mu \lambda^{1-\mu} d\lambda w_1(\phi)d\phi ; \quad B_\mu = \frac{2-\mu}{\lambda_1^{2-\mu} \lambda_0^{2-\mu}} ; \quad (0 < \lambda_0 \leq \lambda_1 < \infty) \left. \vphantom{\frac{2-\mu}{\lambda_1^{2-\mu} \lambda_0^{2-\mu}}} \right\} , \mu \geq 0. \quad (3.5)$$

$$0 \leq \phi \leq 2\pi$$

for the simple geometry of Figure 3.1, where the possible location of the source is in the region Λ_S . Other, more complex geometries may be handled in the same fashion, but this rather simple model often gives reasonable and representative results.

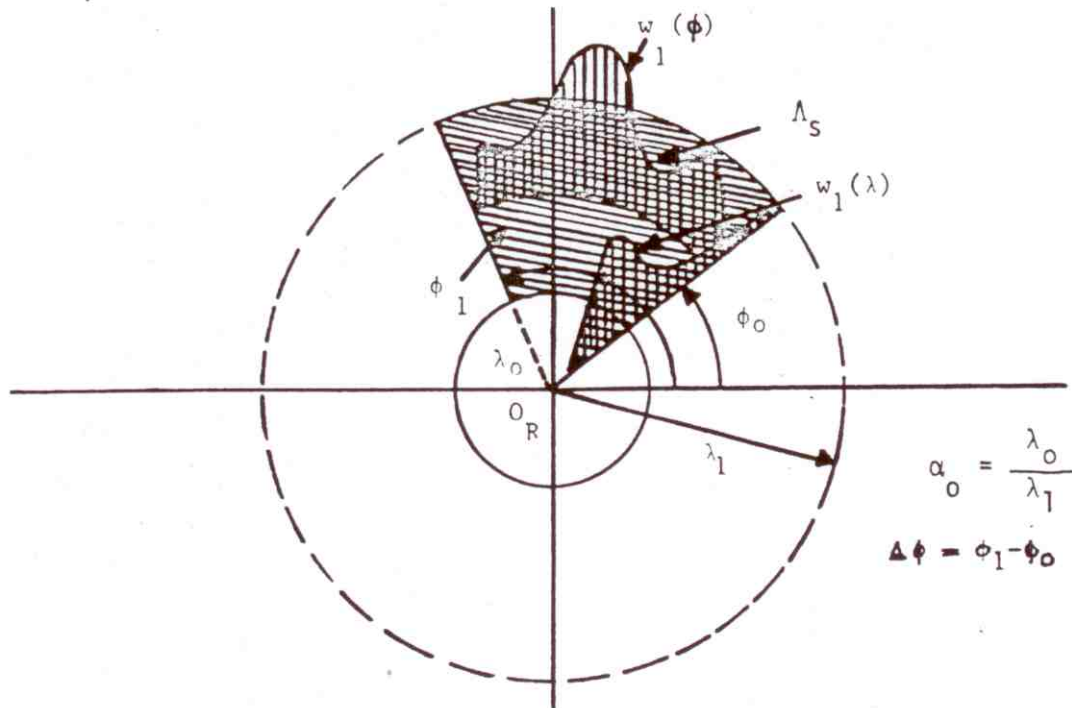


Figure 3.1. Schema of $w_1(\lambda)$, $w_1(\phi)$, Eq. (3.5); $\alpha_0 (\equiv \lambda_0/\lambda_1)$ ratio of inner to outer radii.

